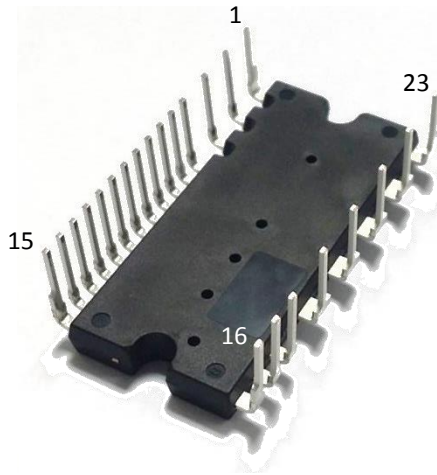


## External View



Size: 33.4 x 15 x 3.6 mm

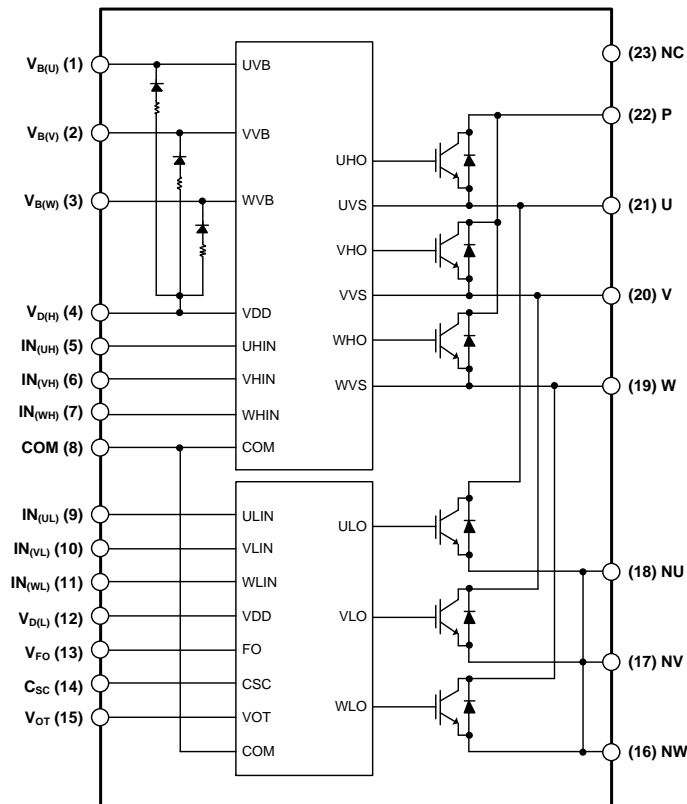
## Features and Functions

- UL Recognized: UL1557 File E345245
- 600V-10A (Trench Shielded Planar Gate IGBT)
- 3 phase Inverter module including HVIC drivers
- Built-in bootstrap diodes with integrated current limiting resistor
- Control supply under-voltage lockout protection (UVLO)
- Over-temperature (OT) protection ( $V_{OT}$ ) - pin open
- Temperature monitoring ( $V_{OT}$ ) - 10k $\Omega$  resistor connection
- Short-circuit current protection ( $C_{SC}$ )
- Fault out signal ( $V_{FO}$ ) corresponding to SC, UV and OT fault
- Wide input interface (3-18V), Schmitt trigger receiver circuit (Active High)
- Isolation ratings of 2000Vrms/min

## Applications

- AC 100~240Vrms class low power motor drives like refrigerators, dishwashers, fan motors, washing machines and air-conditioners

## Internal Equivalent Circuit



## Ordering Information

Part Number	Temperature Range	Package	Environmental
AIM5C10B060M3	150°C	IPM-5	



AOS Green Products use reduced levels of Halogens, and are also RoHS compliant.

Please visit [www.aosmd.com/media/AOSGreenPolicy.pdf](http://www.aosmd.com/media/AOSGreenPolicy.pdf) for additional information.

## Pin Description

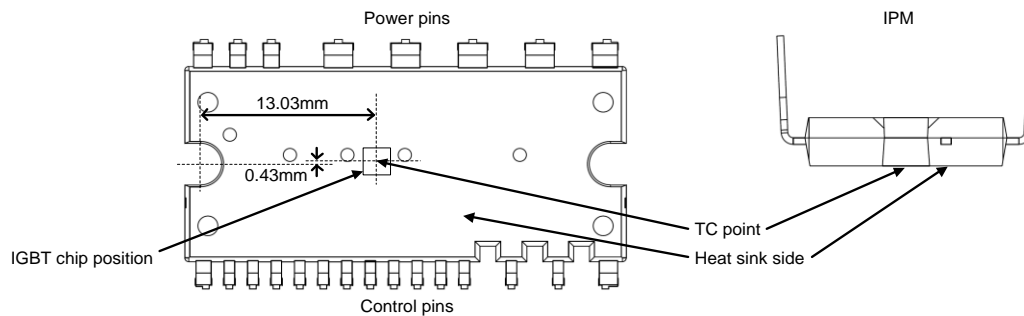
Part Number	Pin Name	Pin Function
1	$V_{B(U)}$	High-Side Bias Voltage for U-Phase IGBT Driving
2	$V_{B(V)}$	High-Side Bias Voltage for V-Phase IGBT Driving
3	$V_{B(W)}$	High-Side Bias Voltage for W-Phase IGBT Driving
4	$V_{D(H)}$	High-Side Common Bias Voltage for IC and IGBTs Driving
5	$IN_{(UH)}$	Signal Input for High-Side U-Phase
6	$IN_{(VH)}$	Signal Input for High-Side V-Phase
7	$IN_{(WH)}$	Signal Input for High-Side W-Phase
8	COM	Common Supply Ground
9	$IN_{(UL)}$	Signal Input for Low-Side U-Phase
10	$IN_{(VL)}$	Signal Input for Low-Side V-Phase
11	$IN_{(WL)}$	Signal Input for Low-Side W-Phase
12	$V_{D(L)}$	Low-Side Common Bias Voltage for IC and IGBTs Driving
13	$V_{FO}$	Fault Output
14	$C_{SC}$	Capacitor (Low-Pass Filter) for Short-circuit Current Detection Input
15	$V_{OT}$	Over-Temperature Output
16	NW	Negative DC-Link Input for W-Phase
17	NV	Negative DC-Link Input for V-Phase
18	NU	Negative DC-Link Input for U-Phase
19	W	Output for W-Phase
20	V	Output for V-Phase
21	U	Output for U-Phase
22	P	Positive DC-Link Input
23	NC	No Connection

**Absolute Maximum Ratings** ( $T_J=25^{\circ}\text{C}$ , Unless Otherwise Specified)

Symbol	Parameter	Conditions	Ratings	Units
<b>Inverter Part</b>				
$V_{PN}$	Supply voltage	Applied between P - NU,NV,NW	450	V
$V_{PN(surge)}$	Supply voltage (surge)	Applied between P - NU,NV,NW	500	V
$V_{CES}$	Collector-emitter voltage		600	V
$I_C$	Output phase current	$T_C=25^{\circ}\text{C}$ , $T_J<150^{\circ}\text{C}$	10	A
		$T_C=100^{\circ}\text{C}$ , $T_J<150^{\circ}\text{C}$	5	A
$I_{PK}$	Output peak phase current	$T_C=25^{\circ}\text{C}$ , less than 1ms pulse width	20	A
$t_{SC}$	Short circuit withstand time	$V_{PN}\leq 400\text{V}$ , $T_J=150^{\circ}\text{C}$ , $V_D=15\text{V}$ (Note 1)	5	$\mu\text{s}$
$P_C$	Collector dissipation	$T_C=25^{\circ}\text{C}$ , per 1 chip	23	W
$T_J$	Operating junction temperature		-40~+150	$^{\circ}\text{C}$
<b>Control (Protection) Part</b>				
$V_D$	Control supply voltage	Applied between $V_{D(H)}$ -COM, $V_{D(L)}$ -COM	25	V
$V_{DB}$	High-side control bias voltage	Applied between $V_{B(U)}$ -U, $V_{B(V)}$ -V, $V_{B(W)}$ -W	25	V
$V_{IN}$	Input voltage	Applied between $IN_{(UH)}$ , $IN_{(VH)}$ , $IN_{(WH)}$ , $IN_{(UL)}$ , $IN_{(VL)}$ , $IN_{(WL)}$ - COM	-0.5~ $V_D+0.5$	V
$V_{FO}$	Fault output supply voltage	Applied between $V_{FO}$ - COM	-0.5~ $V_D+0.5$	V
$I_{FO}$	Fault output current	Sink current at $V_{FO}$ terminal	1	mA
$V_{SC}$	Current sensing input voltage	Applied between $C_{SC}$ - COM	-0.5~5+0.5	V
$V_{OT}$	Temperature output	Applied between $V_{OT}$ - COM	-0.5~5+0.5	V
<b>Total System</b>				
$V_{PN(PROT)}$	Self protection supply voltage limit (Short-circuit protection capability)	$V_D=13.5\sim 16.5\text{V}$ , Inverter part $T_J=150^{\circ}\text{C}$ , Non-repetitive, less than 2 $\mu\text{s}$	400	V
$T_C$	Module case operation temperature	Measurement point of $T_C$ is provided in Figure 1	-30~+125	$^{\circ}\text{C}$
$T_{STG}$	Storage temperature		-40~+150	$^{\circ}\text{C}$
$V_{ISO}$	Isolation voltage	60Hz, sinusoidal, AC 1min, between connected all pins and heat sink plate	2000	$V_{rms}$

**Note:**

1. Allowed number of short circuits: <1000; time between short circuit: >1s.



**Figure 1.  $T_C$  Measurement Point.**

**Thermal Resistance**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
$R_{th(j-c)Q}$	Junction to case thermal resistance (Note 2)	Inverter IGBT part (per 1/6 module)	-	-	5.4	K/W
$R_{th(j-c)F}$		Inverter FWD part (per 1/6 module)	-	-	6.9	K/W

**Note:**

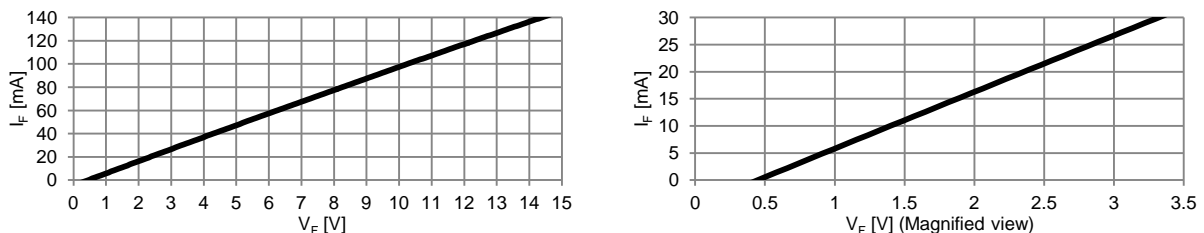
2. For the measurement point of case temperature ( $T_C$ ), please refer to Figure 1.

**Electrical Characteristics** (T<sub>J</sub>=25°C, Unless Otherwise Specified)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units	
<b>Inverter Part</b>							
V <sub>CE(SAT)</sub>	Collector-emitter saturation voltage	V <sub>D</sub> =V <sub>DB</sub> =15V, V <sub>IN</sub> =5V	I <sub>C</sub> =5A, T <sub>J</sub> =25°C	-	1.60	2.00	V
			I <sub>C</sub> =5A, T <sub>J</sub> =125°C	-	1.90	-	V
V <sub>F</sub>	FWD forward voltage	V <sub>IN</sub> =0	I <sub>F</sub> =5A, T <sub>J</sub> =25°C	-	1.80	2.20	V
t <sub>ON</sub>	Switching times	V <sub>PN</sub> =300V, V <sub>D</sub> =V <sub>DB</sub> =15V I <sub>C</sub> =5A, T <sub>J</sub> =25°C, V <sub>IN</sub> =0V ↔ 5V Inductive load (high-side)		0.30	0.60	1.10	µs
t <sub>C(ON)</sub>				-	0.10	0.20	µs
t <sub>OFF</sub>				-	1.00	1.50	µs
t <sub>C(OFF)</sub>				-	0.20	0.40	µs
t <sub>tr</sub>				-	0.30	-	µs
I <sub>CES</sub>	Collector-emitter leakage current	V <sub>CE</sub> =V <sub>CES</sub>	T <sub>J</sub> =25°C	-	-	1	mA
			T <sub>J</sub> =125°C	-	-	10	mA
<b>Control Part</b>							
I <sub>QDH</sub>	Quiescent V <sub>D</sub> supply current	V <sub>D(H)</sub> =15V, I <sub>N(UH, VH, WH)</sub> =0V	V <sub>D(H)</sub> - COM	-	-	0.1	mA
I <sub>QDL</sub>		V <sub>D(L)</sub> =15V, I <sub>N(UL, VL, WL)</sub> =0V	V <sub>D(L)</sub> - COM	-	-	2.1	mA
I <sub>QDB</sub>	Quiescent V <sub>DB</sub> supply current	V <sub>DB</sub> =15V, I <sub>N(UH, VH, WH)</sub> =0V	V <sub>B(U)-U</sub> , V <sub>B(V)-V</sub> , V <sub>B(W)-W</sub>	-	-	0.3	mA
V <sub>SC(ref)</sub>	Short-circuit trip level	V <sub>D</sub> =15V	(Note 3)	0.455	0.480	0.505	V
UV <sub>DT</sub>	Supply circuit under-voltage protection	Trip level		9.0	10.0	11.0	V
UV <sub>DR</sub>		Reset level		10.0	11.0	12.0	V
UV <sub>DBT</sub>		Trip level		8.5	9.5	10.5	V
UV <sub>DBR</sub>		Reset level		9.5	10.5	11.5	V
V <sub>OT</sub>	Temperature output	Pull down R=10kΩ (Note 4)	LVIC temperature=90°C	2.74	2.92	3.10	V
			LVIC temperature=25°C	1.06	1.25	1.43	V
OT <sub>T</sub>	Over-temperature protection	V <sub>D</sub> =15V, detect	Trip level	100	120	140	°C
OT <sub>HYS</sub>	(Note 5)	LVIC temperature	Hysteresis of trip reset	-	10	-	°C
V <sub>FOH</sub>	Fault output voltage	V <sub>SC</sub> =0V, V <sub>FO</sub> circuit: 5kΩ to 5V pull-up		4.9	-	-	V
V <sub>FOL</sub>		V <sub>SC</sub> =1V, V <sub>FO</sub> circuit: 5kΩ to 5V pull-up		-	-	0.5	V
t <sub>FO</sub>	Fault output pulse width	(Note 6)		20	-	-	µs
I <sub>IN</sub>	Input current	V <sub>IN</sub> =5V		-	1.0	-	mA
V <sub>th(on)</sub>	ON threshold voltage				2.3	2.6	V
V <sub>th(off)</sub>	OFF threshold voltage	Applied between I <sub>N(UH)</sub> , I <sub>N(VH)</sub> , I <sub>N(WH)</sub> , I <sub>N(UL)</sub> , I <sub>N(VL)</sub> , I <sub>N(WL)</sub> - COM		0.8	1.2	-	V
V <sub>th(hys)</sub>	ON/OFF threshold hysteresis voltage			-	1.1	-	V
V <sub>F(BSD)</sub>	Bootstrap diode forward voltage	I <sub>F</sub> =10mA including voltage drop by limiting resistor (Note 7)		1.0	1.5	2.0	V
R <sub>BSD</sub>	Built-in limiting resistance	Included in bootstrap diode		80	100	120	Ω

**Note:**

- Short-circuit protection works only for low-sides.
- The IPM does not shutdown IGBTs and output fault signal automatically when temperature rises excessively. When temperature exceeds the protective level that the user defined, the controller (MCU) should stop the IPM. Temperature of LVIC vs. V<sub>OT</sub> output characteristics is described in Figure 3.
- When the LVIC temperature exceeds OT Trip temperature level (OT<sub>T</sub>), OT protection works and fault outputs.
- Fault signal F<sub>O</sub> outputs when SC, UV or OT protection works. F<sub>O</sub> pulse width is different for each protection mode. At SC failure, F<sub>O</sub> pulse width is a fixed width (minimum 20µs), but at UV or OT failure, F<sub>O</sub> outputs continuously until recovering from UV or OT state. (But minimum F<sub>O</sub> pulse width is 20µs).
- The characteristics of bootstrap diode are described in Figure 2.



**Figure 2. Built-in Bootstrap Diode V<sub>F</sub>-I<sub>F</sub> Characteristic (@T<sub>a</sub>=25°C).**

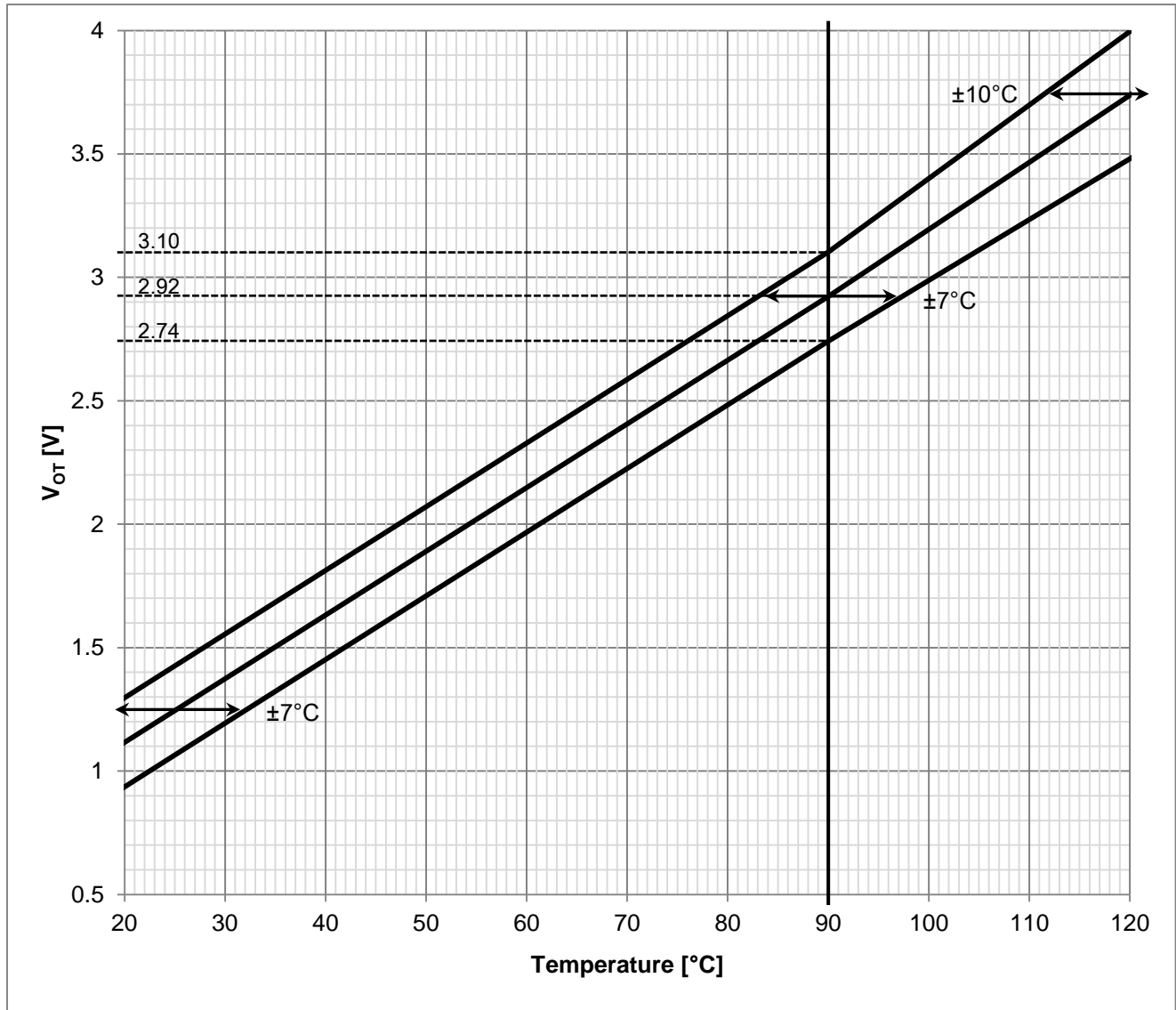
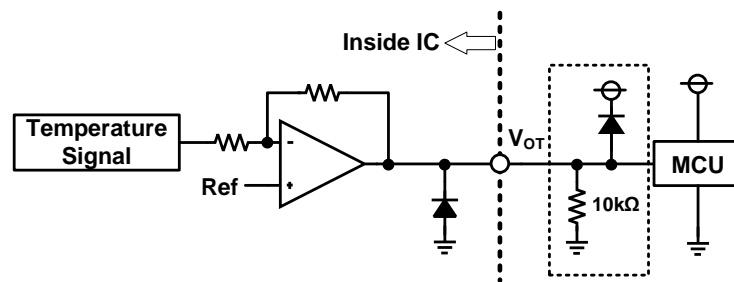


Figure 3. Temperature of LVIC vs. V<sub>OT</sub> Output Characteristics.



- (1) Connect 10kΩ to V<sub>OT</sub> pin if temperature monitoring function is used and leave the V<sub>OT</sub> pin open (no connect) if not using temperature monitoring and use internal over-temperature shutdown function.
- (2) In the case of using V<sub>OT</sub> with low voltage controller like 3.3V MCU, V<sub>OT</sub> output might exceed control supply voltage 3.3V when temperature rises excessively. If system uses low voltage controller, it is recommended to insert a clamp diode between control supply of the controller and V<sub>OT</sub> output for preventing over voltage destruction.

Figure 4. V<sub>OT</sub> Output Circuit.

## Mechanical Characteristics and Ratings

Parameter	Conditions	Min.	Typ.	Max.	Units
Mounting torque	Mounting screw: M3 (Note 8)   Recommended 0.69N m	0.59	0.69	0.78	N m
Weight		-	5.25	-	g
Flatness	Refer Figure 5	-50	-	100	$\mu\text{m}$

**Note:**

8. Plain washers (ISO 7089~7094) are recommended.

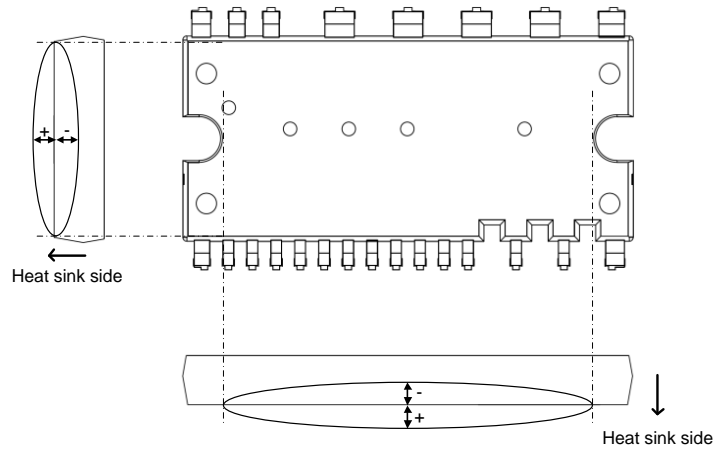


Figure 5. Flatness Measurement Position.

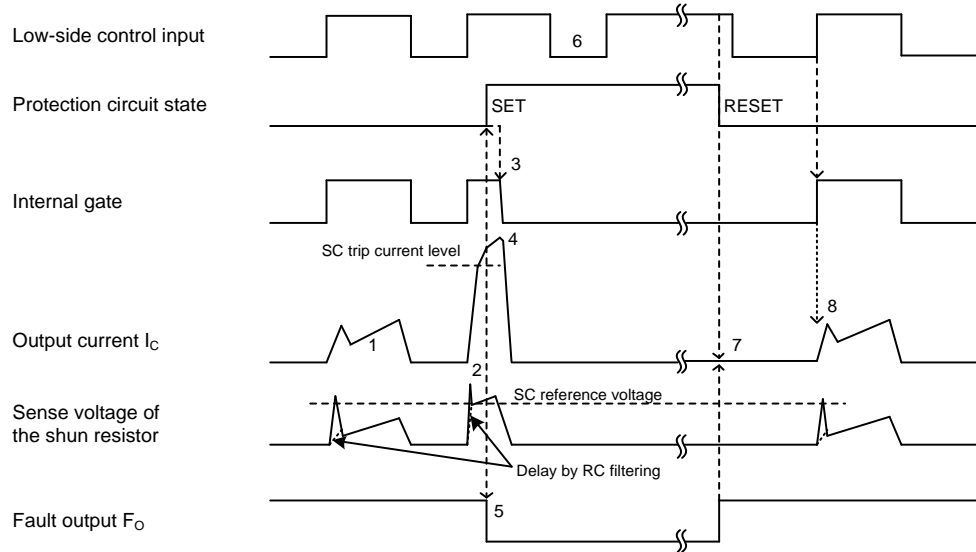
## Recommended Operation Conditions

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
$V_{PN}$	Supply voltage	Applied between P-NU, NV, NW	0	300	400	V
$V_D$	Control supply voltage	Applied between $V_{D(H)} - \text{COM}$ , $V_{D(L)} - \text{COM}$	13.5	15.0	16.5	V
$V_{DB}$	High-side bias voltage	Applied between $V_{B(U)} - U$ , $V_{B(V)} - V$ , $V_{B(W)} - W$	13.5	15.0	18.5	V
$\frac{dV_D}{dt}$ , $\frac{dV_{DB}}{dt}$	Control supply variation		-1	-	1	V/ $\mu\text{s}$
$t_{\text{dead}}$	Arm shoot-through blocking time	For each input signal	1.0	-	-	$\mu\text{s}$
$f_{\text{PWM}}$	PWM input frequency	$-40^\circ\text{C} < T_J < 150^\circ\text{C}$	-	-	20	kHz
$P_{\text{WIN(ON)}}$	Minimum input pulse width	(Note 9)	0.4	-	-	$\mu\text{s}$
$P_{\text{WIN(OFF)}}$			0.4	-	-	$\mu\text{s}$
COM	COM variation	Between COM - NU, NV, NW (including surge)	-5.0	-	+5.0	V

**Note:**

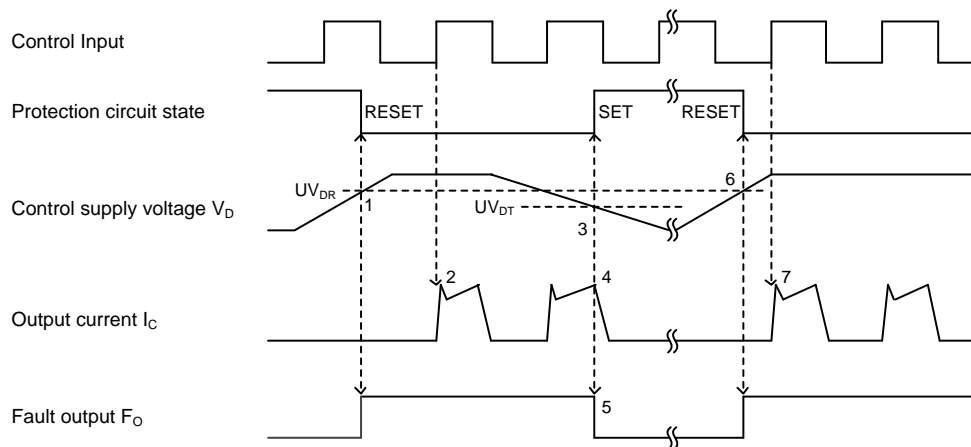
9. IPM might not make response if the input signal pulse width is less than  $P_{\text{WIN(ON)}}$ ,  $P_{\text{WIN(OFF)}}$ .

## Time Charts of the IPM Protective Function



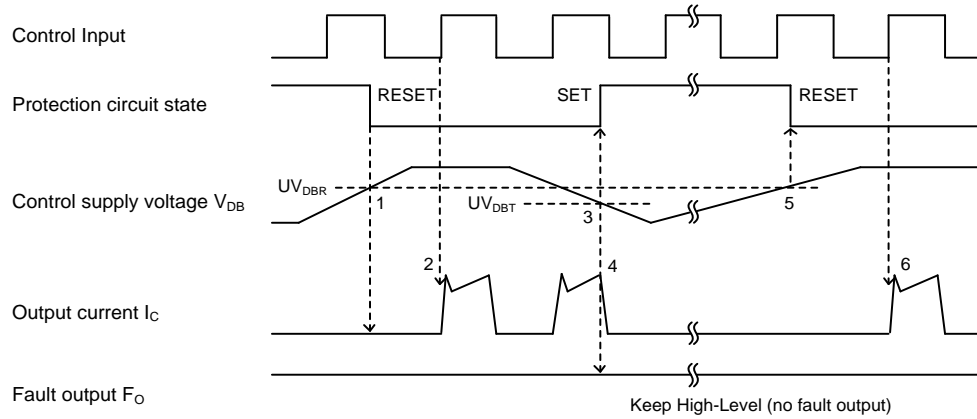
- (1) Normal operation: IGBT turns on and outputs current.
- (2) Short-circuit current detection (SC trigger).
- (3) All low-side IGBT's gates are hard interrupted.
- (4) All low-side IGBTs turn OFF.
- (5)  $F_O$  outputs for  $t_{FO}$ =minimum  $20\mu s$ .
- (6) Input = "L" : IGBT OFF.
- (7) Fault output finish, but output current will not turn on until next ON signal (L→H).
- (8) Normal operation: IGBT turns on and outputs current.

**Figure 6. Short-Circuit Protection (Low-side Operation only with the external shunt resistor and RC filter).**



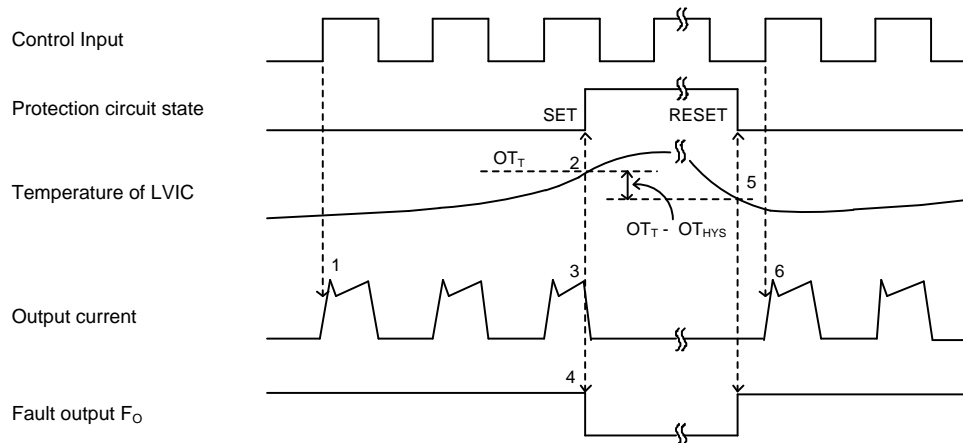
- (1) Control supply voltage  $V_D$  exceeds under voltage reset level ( $UV_{DR}$ ), but IGBT turns on by next ON signal (L→H).
- (2) Normal operation: IGBT turns on and outputs current.
- (3)  $V_D$  level drops to under voltage trip level ( $UV_{DT}$ ).
- (4) All low-side IGBTs turn OFF in spite of control input condition.
- (5)  $F_O$  output for  $t_{FO}$ =minimum  $20\mu s$ , but output is extended during  $V_D$  keeps below  $UV_{DR}$ .
- (6)  $V_D$  level reaches  $UV_{DR}$ .
- (7) Normal operation: IGBT turns on and outputs current.

**Figure 7. Under-Voltage Protection (Low-side,  $UV_D$ ).**



- (1) Control supply voltage  $V_{DB}$  rises. After the voltage reaches under voltage reset level  $UV_{DBR}$ , IGBT turns on by next ON signal (L→H).
- (2) Normal operation: IGBT turns on and outputs current.
- (3)  $V_{DB}$  level drops to under voltage trip level ( $UV_{DBT}$ ).
- (4) All high-side IGBTs turn OFF in spite of control input condition, but there is no FO signal output.
- (5)  $V_{DB}$  level reaches  $V_{DBR}$ .
- (6) Normal operation: IGBT turns on and outputs current.

**Figure 8. Under-Voltage Protection (High-side,  $UV_{DB}$ ).**

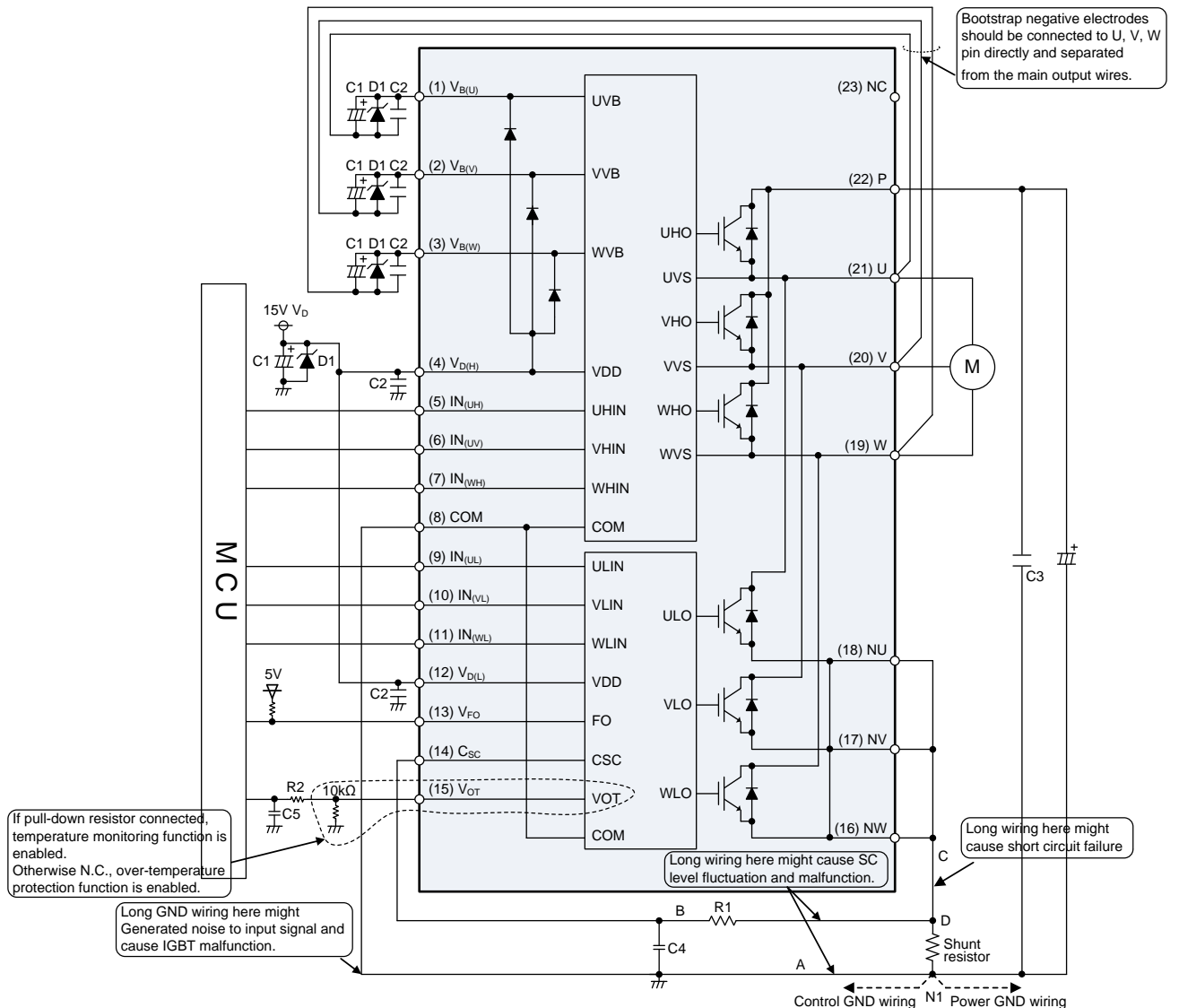


- (1) Normal operation: IGBT turns on and outputs current.
- (2) LVIC temperature exceeds over-temperature trip level ( $OT_T$ ).
- (3) All low-side IGBTs turn OFF in spite of control input condition.
- (4)  $F_o$  outputs for  $t_{FO}$ =minimum 20 $\mu$ s, but output is extended during LVIC temperature keeps over  $OT_T$ .
- (5) LVIC temperature drops to over-temperature reset level.
- (6) Normal operation: IGBT turns on by the next ON signal (L→H).

**Figure 9. Over-Temperature Protection (Low-side, Detecting LVIC temperature).**

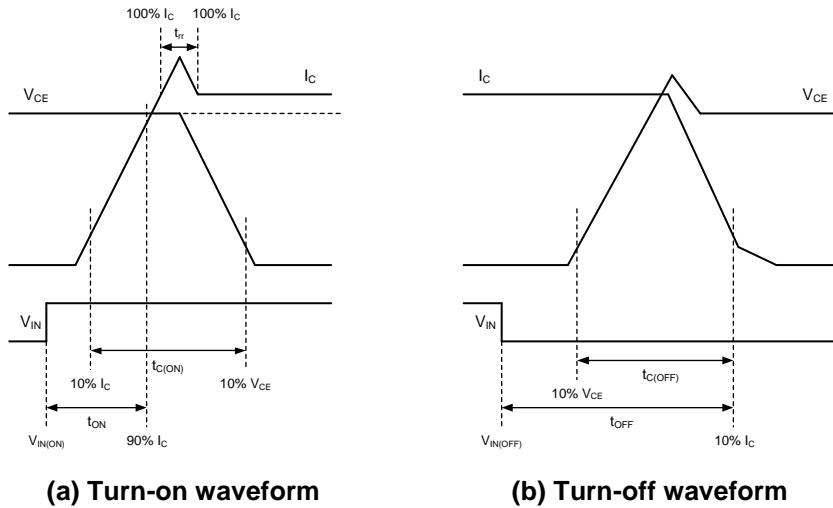


### Example of Application Circuit



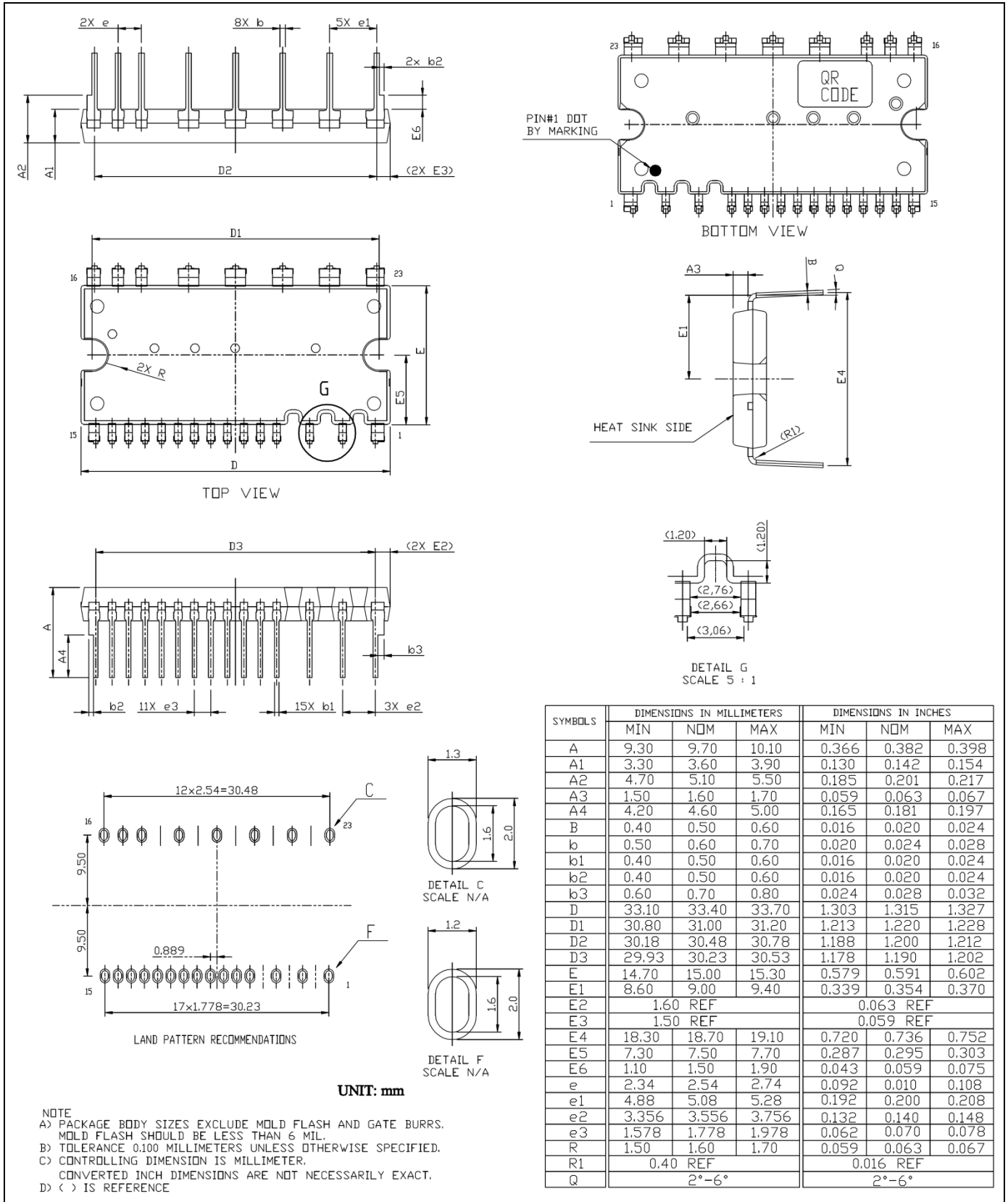
- (1) If control GND is connected with power GND by common broad pattern, it may cause malfunction by power GND fluctuation. It is recommended to control GND and power GND at only a point N1 (near the terminal of shunt resistor).
- (2) It is recommended to insert zener diode D1 (24V/1W) between each pair of control supply pins to prevent surge destruction.
- (3) To prevent surge destruction, the wiring between the smoothing capacitor and the P, N1 terminals should be as short as possible. Generally a 0.1~0.22 $\mu$ F snubber capacitor C3 between the P-N1 terminals is recommended.
- (4) R1, C4 of RC filter for preventing protection circuit malfunction is recommended to select tight tolerance, temp-compensated type. The time constant R1C4 should be set so that SC current is shut down within 2 $\mu$ s. (1.5 $\mu$ s~2 $\mu$ s is general value). SC interrupting time might vary with the wiring pattern, so the enough evaluation on the real system is necessary.
- (5) R2, C5 of RC filter for temperature monitoring is recommended to select tight tolerance, temp-compensated type. The time constant R2C5 should be set so that VOT has noise immunity. Recommended value of R2 and C5 are 2k $\Omega$  and 10nF (10 to 30 $\mu$ s range of time constant).
- (6) To prevent malfunction, the wiring of A, B, C should be as short as possible.
- (7) The point D at which the wiring to  $C_{SC}$  filter is divided should be near the terminal of shunt resistor. NU, NV, NW pins should be connected at near NU, NV, NW pins.
- (8) All capacitors should be mounted as close to the terminals as possible. (C1: good temperature, frequency characteristic electrolytic type and C2: 0.22 $\mu$ ~2 $\mu$ F, good temperature, frequency and DC bias characteristic ceramic type are recommended).
- (9) Input drive is high-active type. There is a minimum 3.5k $\Omega$  pull-down resistor in the input circuit of IC. To prevent malfunction, the wiring of each input should be as short as possible. When using RC coupling circuit, make sure the input signal level meet the turn-on and turn-off threshold voltage.

- (10)  $V_{FO}$  output is open drain type. It should be pulled up to MCU or control power supply (e.g. 5V, 15V) by a resistor that makes  $I_{FO}$  up to 1mA. ( $I_{FO}$  is estimated roughly by the formula of control power supply voltage divided by pull-up resistor. In the case of pulled up to 5V, 10k $\Omega$  (over 5k $\Omega$ ) is recommended).
- (11) Thanks to build-in HVIC, direct coupling to MCU without any opto-coupler or transformer isolation is possible.
- (12) If high frequency noise superimposed to the control supply line, IC malfunction might happen and cause IPM erroneous operation. To avoid such problem, line ripple voltage should meet  $dV/dt \leq \pm 1V/\mu s$ ,  $V_{ripple} \leq 2Vp-p$ .
- (13) For IPM, it isn't recommended to drive same load by parallel connection with other phase IGBT or other IPM.



**Figure 10. Switching Times Definition.**

**Package Dimensions**



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